

MAT225 Section Summary: 4.2

Null spaces, column spaces, and linear transformations
Summary

$$\bar{x} \in \mathbb{R}^n$$

The solution set of the homogeneous equation $A_{m \times n} \bar{x} = \bar{0}$ forms a subspace of \mathbb{R}^n , as one can see easily:

$$\bar{0} \in \mathbb{R}^n$$

1. the zero vector is in the solution set (the trivial solution);
2. Consider two vectors in the solution set, \mathbf{u} and \mathbf{v} : then $A(\mathbf{u} + \mathbf{v}) = A\mathbf{u} + A\mathbf{v} = \mathbf{0} + \mathbf{0} = \mathbf{0}$, so the solution set is closed under addition.
3. Consider a vectors in the solution set, \mathbf{u} and an arbitrary constant c : then $A(c\mathbf{u}) = cA\mathbf{u} = \mathbf{0}$, so the solution set is closed under scalar multiplication.

Null space of an $m \times n$ matrix A : the null space of an $m \times n$ matrix A , denoted $\text{Nul } A$, is the solution set of the homogeneous equation $A\mathbf{x} = \mathbf{0}$. It is the set of all $\mathbf{x} \in \mathbb{R}^n$ that are mapped to the zero vector of \mathbb{R}^m by the transformation $\mathbf{x} \rightarrow A\mathbf{x}$.

Theorem 2: The null space of an $m \times n$ matrix A is a subspace of \mathbb{R}^n .

Example: #3, p. 234.

$$A = \begin{bmatrix} 1 & 3 & 5 & 0 \\ 0 & 1 & 4 & -2 \end{bmatrix} \quad \text{Nul } A \subseteq \mathbb{R}^4 \quad A\bar{x} = \bar{0} .$$

$$x_1 = 7x_3 - 6x_4$$

$$x_2 = -4x_3 + 2x_4$$

$$x_3 = x_3$$

$$x_4 = x_4$$

$$\bar{x} = \begin{bmatrix} 7x_3 - 6x_4 \\ -4x_3 + 2x_4 \\ x_3 \\ x_4 \end{bmatrix} = x_3 \begin{bmatrix} 7 \\ -4 \\ 1 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} -6 \\ 2 \\ 0 \\ 1 \end{bmatrix}$$

Notice that the number of vectors in the spanning set for $\text{Nul } A$ equals the number of free variables in the equation $A\mathbf{x} = \mathbf{0}$.

Column space: Another subspace associated with the matrix A is the column space, $\text{Col } A$, defined as the span of the columns of A : $\text{Col } A = \text{Span } \{a_1, \dots, a_n\}$. As a span, it is clearly a subspace (Theorem 3).

$\text{Col } A = \{\mathbf{b} : \mathbf{b} = Ax \text{ for some } \mathbf{x} \in \mathbb{R}^n\}$, which says that $\text{Col } A$ is the range of the transformation $\mathbf{x} \rightarrow Ax$.

Example: #16, p. 234

$$\left\{ \begin{bmatrix} b - c \\ 2b + c + d \\ 5c - 4d \\ d \end{bmatrix} : b, c, d \text{ real} \right\}$$

$$\tilde{v} = b \begin{bmatrix} 1 \\ 2 \\ 0 \\ 0 \end{bmatrix} + c \begin{bmatrix} -1 \\ 1 \\ 5 \\ 0 \end{bmatrix} + d \begin{bmatrix} 0 \\ 1 \\ -4 \\ 1 \end{bmatrix}$$

$$A_{4 \times ?} = \begin{bmatrix} 1 & -1 & 0 \\ 2 & 1 & 1 \\ 0 & 5 & -4 \\ 0 & 0 & 1 \end{bmatrix}$$

The null space lives in the row space of the matrix A , and the column space lives in the column space of A .

Example: #22, p. 235

Linear Transformation: A linear transformation T from a vector space V into a vector space W is a rule that assigns to each vector \mathbf{x} in V a unique vector $T(\mathbf{x})$ in W , such that

1. $T(\mathbf{u} + \mathbf{v}) = T(\mathbf{u}) + T(\mathbf{v})$

$$2. T(c\mathbf{u}) = cT(\mathbf{u})$$

The kernel (or null space) of T is the set of \mathbf{u} such that $T(\mathbf{u}) = \mathbf{0}$. The range of T is the set of all vectors in W of the form $T(\mathbf{x})$ for some \mathbf{x} in V .

Example: #30, p. 235 $T: V \rightarrow W$

- ① $T(\bar{0}) = \bar{0} \Rightarrow \bar{0} \in \text{Range of } T$
- ② Given $T(\bar{x}) + T(\bar{w})$; $T(\bar{x}) + T(\bar{w}) = T(\bar{x} + \bar{w})$
So $T(\bar{x}) + T(\bar{w})$ is in the Range, image of $\bar{x} + \bar{w}$;
- ③ $cT(\bar{x}) = T(c\bar{x})$, so $cT(\bar{x})$ is in the range of T , image of $c\bar{x}$. So $T(V)$ is a subspace of W .

Examples of linear transformations include matrix transformations, as well as differentiation in the vector space of differentiable functions defined on an interval (a, b) .

Example: #33, p. 235 $M_{2 \times 2}$, real co-efficients.

$T: M_{2 \times 2} \rightarrow M_{2 \times 2}$ by $T(A) = A + A^T$

$$\begin{aligned} a) T(A_1 + A_2) &= A_1 + A_2 + (A_1 + A_2)^T = A_1 + A_2 + A_1^T + A_2^T \\ &= A_1 + A_1^T + A_2 + A_2^T = T(A_1) + T(A_2) \\ T(cA_1) &= cA_1 + (cA_1)^T = cA_1 + cA_1^T = cT(A_1) \end{aligned}$$

Continued below...

Column space : is it a subspace?

$$C = \left\{ \bar{b} \in R^m \mid \exists \bar{x} \in \mathbb{R}^3 \quad A\bar{x} = \bar{b} \right\}$$

$$① \bar{0} \in C, \text{ because } A\bar{0} = \bar{0}$$

$$② \text{ Given } \bar{b}_1 + \bar{b}_2 \text{ in } C$$

$$A(\bar{x}_1 + \bar{x}_2) = A\bar{x}_1 + A\bar{x}_2 = \bar{b}_1 + \bar{b}_2$$

So $\bar{b}_1 + \bar{b}_2$ is in C , the image of
 $\bar{x}_1 + \bar{x}_2$.

(3) $c\bar{b}_1$ is in C , the image of $c\bar{x}_1$:

$$A(c\bar{x}_1) = cA\bar{x}_1 = c\bar{b}_1, \quad \checkmark$$

#33 continued...

b. Let $B \in M_{2 \times 2} / B^T = B$. Find $A \in M_{2 \times 2} / B = T(A)$.

$$T(A) = A + A^T = \underbrace{B}_{\text{domain } T(A)}$$

$$\text{Let } A = \frac{1}{2}B ; \quad T(A) = \frac{1}{2}B + \frac{1}{2}B^T = \frac{1}{2}B + \frac{1}{2}B \\ = B \quad \checkmark$$

c) Show that $\text{Range}(T) \text{ is } \{B \in M_{2 \times 2} / B^T = B\}$

$$T(A) = A + A^T$$

$$[T(A)]^T = (A + A^T)^T = A^T + (A^T)^T = A^T + A \\ = A + A^T = T(A).$$

So every $T(A)$ is equal to its own transpose
 \checkmark

d. Describe the kernel of T

$$T(A) = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} = A + A^T$$

$$A = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \text{ also satisfies } T(A) = 0$$

So the kernel is $\mathbf{C} \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$, a
 one dimensional subspace of $M_{2 \times 2}$.

