Section 1.2: Row Reduction and Echelon Forms

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Abstract

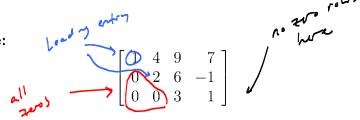
In this section we consider an algorithm (Gaussian elimination with partial pivoting) for reducing a system of equations to reduced echelon form, which is unique and allows us to write the solution set of a linear system. The solution may contain free parameters, meaning that there are infinitely many solutions.

Definition: A rectangular matrix is in **row echelon form** if it has the following three properties:

- 1. zero rows are at the bottom;
- 2. Leading (non-zero) entries of α row move right as one descends the matrix; and

3. All entries below a row's leading entry are zero.

Example:



Definition: A matrix in echelon form is in **reduced row echelon** form if it has the additional two properties:

- 1. The leading entry in each non-zero row is 1, and
- 2. Each leading entry is the only non-zero entry in its column.

Example: The matrix above in reduced row echelon form is

$$\begin{bmatrix} 1 & 4 & 9 & 7 \\ 0 & 2 & 6 & -1 \\ 0 & 0 & 3 & 1 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 0 & 10 \\ 0 & 1 & 0 & -3/2 \\ 0 & 0 & 1 & 1/3 \end{bmatrix}$$

Theorem: Each matrix is row-equivalent to one and only one reduced row echelon matrix.

Example: The 4×4 identity matrix I_4 :

$$\left[\begin{array}{cccc}
1 & 0 & 0 & 0 \\
0 & 1 & 0 & 0 \\
0 & 0 & 1 & 0 \\
0 & 0 & 0 & 1
\end{array}\right]$$

Note: The uniqueness of the reduced row echelon matrix implies that the positions of the leading non-zero entries are fixed in stone for a given matrix. These positions are known as **pivot positions**. A **pivot column** of a matrix is one that contains a pivot position.

This leads to the following definitions:

- basic variables: variables corresponding to pivot positions
- free variables: variables other than basic variables

reduced

Gaussian elimination (using partial pivoting) for row reduction:

- 1. Begin with the leftmost column. This is a pivot column, with pivot position at the top. Select largest entry (in terms of magnitude) in the pivot column, and interchange rows to move this entry into the pivot position.
- 2. Use row replacement to create zeros in all positions below the pivot.
- 3. Iterate, using the submatrix below the pivot row and to the right of the pivot column.
- 4. Beginning with the rightmost pivot and working left, create zeros above each pivot.
- 5. Scale all pivot rows by the pivot value, so that pivots are 1.

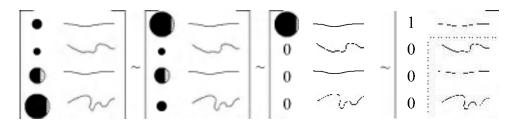


Figure 1: Here's my image of the partial pivoting process: notice that it's recursive, and we keep paring down the size of the matrix (dotted part in the last panel) until we run out of matrix to work on!

Example: Consider Exercise #12, p. 25. In this example, we have an augmented system of three equations in four unknowns. Hence, we know that we will not have enough information to have a unique solution: the question then is whether we are consistent, and how to express the solution set.

$$\begin{bmatrix} 1 & -7 & 0 & 6 & 5 \\ 0 & 0 & 1 & -2 & -3 \\ -1 & 7 & -4 & 2 & 7 \end{bmatrix} \sim \begin{bmatrix} 1 & -7 & 0 & 6 & 5 \\ 0 & 0 & 1 & -7 & -3 \\ 0 & 0 & -4 & 9 & 12 \end{bmatrix} \sim \begin{bmatrix} 1 & -7 & 0 & 6 & 5 \\ 0 & 0 & -4 & 9 & 12 \end{bmatrix} \sim \begin{bmatrix} 1 & -7 & 0 & 6 & 5 \\ 0 & 0 & -4 & 9 & 12 \end{bmatrix} \sim \begin{bmatrix} 1 & -7 & 0 & 6 & 5 \\ 0 & 0 & -4 & 9 & 12 \end{bmatrix} \sim \begin{bmatrix} 1 & -7 & 0 & 6 & 5 \\ 0 & 0 & -4 & 9 & 12 \end{bmatrix} \sim \begin{bmatrix} 1 & -7 & 0 & 6 & 5 \\ 0 & 0 & -4 & 9 & 12 \end{bmatrix} \sim \begin{bmatrix} 1 & -7 & 0 & 6 & 5 \\ 0 & 0 & -4 & 9 & 12 \end{bmatrix} \sim \begin{bmatrix} 1 & -7 & 0 & 6 & 5 \\ 0 & 0 & -4 & 9 & 12 \end{bmatrix} \sim \begin{bmatrix} 1 & -7 & 0 & 6 & 5 \\ 0 & 0 & -4 & 9 & 12 \\ 0 & 0 & 6 & 0 & 0 \end{bmatrix}$$

Our author suggests solving systems by pushing all the way to reduced echelon form. Here's his process for using row reduction to solve a linear system:

- 1. Write the augmented matrix of the system
- 2. Use the row reduction algorithm to obtain an equivalent augmented matrix in echelon form. Decide whether the system is consistent. If so, continue; else stop.
- 3. Continue row reduction to obtain the reduced echelon form.
- 4. Write the system of equations corresponding to the matrix in reduced echelon form.
- 5. Rewrite each nonzero equation from step 4 so that its one basic variable is expressed in terms of any free variables appearing in the equation.

$$x_1 + -7x_2 + 6x_4 = 5$$

$$x_3 = -3 + 2x_4$$

$$x_4 = -3$$

Example: #7, p. 25 (what's the geometry like?)
$$\begin{bmatrix} 1 & 3 & 4 & 7 \\ 3 & 9 & 7 & 6 \end{bmatrix}$$

$$\sim \begin{bmatrix} 3 & 9 & 7 & 6 \\ 1 & 3 & 4 & 7 \end{bmatrix} \sim \begin{bmatrix} 3 & 9 & 7 & 6 \\ 0 & 0 & 5 \\ 3 & 5 \end{bmatrix} - 30 + 3$$

$$\sim \begin{bmatrix} 3 & 9 & 7 & 6 \\ 0 & 0 & 1 & 3 \end{bmatrix} \sim \begin{bmatrix} 3 & 9 & 0 & -15 \\ 0 & 0 & 1 & 3 \end{bmatrix} \sim \begin{bmatrix} 3 & 9 & 0 & -15 \\ 0 & 0 & 1 & 3 \end{bmatrix} = \begin{bmatrix} 3 & 9 & 0 & -15 \\ 0 & 0 & 1 & 3 \end{bmatrix} = \begin{bmatrix} 3 & 9 & 0 & -15 \\ 0 & 0 & 1 & 3 \end{bmatrix} = \begin{bmatrix} 3 & 9 & 0 & -15 \\ 0 & 0 & 1 & 3 \end{bmatrix} = \begin{bmatrix} 3 & 9 & 0 & -15 \\ 0 & 0 & 1 & 3 \end{bmatrix} = \begin{bmatrix} 3 & 9 & 0 & -15 \\ 0 & 0 & 1 & 3 \end{bmatrix} = \begin{bmatrix} 3 & 9 & 0 & -15 \\ 0 & 0 & 1 & 3 \end{bmatrix} = \begin{bmatrix} 3 & 9 & 0 & -15 \\ 0 & 0 & 1 & 3 \end{bmatrix} = \begin{bmatrix} 3 & 9 & 0 & -15 \\ 0 & 0 & 1 & 3 \end{bmatrix} = \begin{bmatrix} 3 & 9 & 0 & -15 \\ 0 & 0 & 1 & 3 \end{bmatrix} = \begin{bmatrix} 3 & 9 & 0 & -15 \\ 0 & 0 & 1 & 3 \end{bmatrix} = \begin{bmatrix} 3 & 9 & 0 & -15 \\ 0 & 0 & 1 & 3 \end{bmatrix} = \begin{bmatrix} 3 & 9 & 0 & -15 \\ 0 & 0 & 1 & 3 \end{bmatrix} = \begin{bmatrix} 3 & 9 & 0 & -15 \\ 0 & 0 & 1 & 3 \end{bmatrix} = \begin{bmatrix} 3 & 9 & 0 & -15 \\ 0 & 0 & 1 & 3 \end{bmatrix} = \begin{bmatrix} 3 & 9 & 0 & -15 \\ 0 & 0 & 1 & 3 \end{bmatrix} = \begin{bmatrix} 3 & 9 & 0 & -15 \\ 0 & 0 & 1 & 3 \end{bmatrix} = \begin{bmatrix} 3 & 9 & 0 & -15 \\ 0 & 0 & 1 & 3 \end{bmatrix} = \begin{bmatrix} 3 & 9 & 0 & -15 \\ 0 & 0 & 1 & 3 \end{bmatrix} = \begin{bmatrix} 3 & 9 & 0 & -15 \\ 0 & 0 & 1 & 3 \end{bmatrix} = \begin{bmatrix} 3 & 9 & 0 & -15 \\ 0 & 0 & 1 & 3 \end{bmatrix} = \begin{bmatrix} 3 & 9 & 0 & -15 \\ 0 & 0 & 1 & 3 \end{bmatrix} = \begin{bmatrix} 3 & 9 & 0 & -15 \\ 0 & 0 & 1 & 3 \end{bmatrix} = \begin{bmatrix} 3 & 9 & 0 & -15 \\ 0 & 0 & 1 & 3 \end{bmatrix} = \begin{bmatrix} 3 & 9 & 0 & -15 \\ 0 & 0 & 1 & 3 \end{bmatrix} = \begin{bmatrix} 3 & 9 & 0 & -15 \\ 0 & 0 & 1 & 3 \end{bmatrix} = \begin{bmatrix} 3 & 9 & 0 & -15 \\ 0 & 0 & 1 & 3 \end{bmatrix} = \begin{bmatrix} 3 & 9 & 0 & -15 \\ 0 & 0 & 1 & 3 \end{bmatrix} = \begin{bmatrix} 3 & 9 & 0 & -15 \\ 0 & 0 & 1 & 3 \end{bmatrix} = \begin{bmatrix} 3 & 9 & 0 & -15 \\ 0 & 0 & 1 & 3 \end{bmatrix} = \begin{bmatrix} 3 & 9 & 0 & -15 \\ 0 & 0 & 1 & 3 \end{bmatrix} = \begin{bmatrix} 3 & 9 & 0 & -15 \\ 0 & 0 & 1 & 3 \end{bmatrix} = \begin{bmatrix} 3 & 9 & 0 & -15 \\ 0 & 0 & 1 & 3 \end{bmatrix} = \begin{bmatrix} 3 & 9 & 0 & -15 \\ 0 & 0 & 1 & 3 \end{bmatrix} = \begin{bmatrix} 3 & 9 & 0 & -15 \\ 0 & 0 & 1 & 3 \end{bmatrix} = \begin{bmatrix} 3 & 9 & 0 & -15 \\ 0 & 0 & 1 & 3 \end{bmatrix} = \begin{bmatrix} 3 & 9 & 0 & -15 \\ 0 & 0 & 1 & 3 \end{bmatrix} = \begin{bmatrix} 3 & 9 & 0 & -15 \\ 0 & 0 & 1 & 3 \end{bmatrix} = \begin{bmatrix} 3 & 9 & 0 & -15 \\ 0 & 0 & 1 & 3 \end{bmatrix} = \begin{bmatrix} 3 & 9 & 0 & -15 \\ 0 & 0 & 1 & 3 \end{bmatrix} = \begin{bmatrix} 3 & 9 & 0 & -15 \\ 0 & 0 & 1 & 3 \end{bmatrix} = \begin{bmatrix} 3 & 9 & 0 & -15 \\ 0 & 0 & 1 & 3 \end{bmatrix} = \begin{bmatrix} 3 & 9 & 0 & -15 \\ 0 & 0 & 1 & 3 \end{bmatrix} = \begin{bmatrix} 3 & 9 & 0 & -15 \\ 0 & 0 & 1 & 3 \end{bmatrix} = \begin{bmatrix} 3 & 9 & 0 & -15 \\ 0 & 0 & 1 & 3 \end{bmatrix} = \begin{bmatrix} 3 & 9 & 0 & -15 \\ 0 & 0 & 1 & 3 \end{bmatrix} = \begin{bmatrix} 3 & 9 & 0 & -15 \\ 0 & 0 & 1 & 3 \end{bmatrix} = \begin{bmatrix} 3 & 0 & 0$$

General solutions of linear systems are hence given parametrically. If there is a free variable, then there are an infinite number of solutions. If there is a row having its pivot position in the rightmost column, then the system is inconsistent. This is the essence of Theorem 2, p. 24.

Additional problems: #15, #29, #30