## Section 1.4: The Matrix Equation $A\mathbf{x} = \mathbf{b}$

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## Abstract

We encounter yet another representation for a system of linear equations – will it never end?! This is the last we'll examine, and probably the most important. Theorem four pulls all these forms together: spans, pivots, linear combinations, and matrix equations collide!

"A fundamental idea in linear algebra is to view a linear combination of vectors as the product of a matrix and a vector." p. 40

Matrix/vector multiplication is defined. One form that I find particularly useful is the so-called "row-vector rule": a row of the matrix slams into the variable vector  $\mathbf{x}$ , to produce a single entry in the  $\mathbf{b}$  vector.

## Definition: product of matrix A and vector $\mathbf{x}$

If A is an  $m \times n$  matrix, with columns  $\mathbf{a}_1$ ,  $\mathbf{a}_2 \dots$ ,  $\mathbf{a}_n$ , and if  $\mathbf{x}$  is in  $\mathbb{R}^n$ , then the product of A and  $\mathbf{x}$  is the linear combination of the columns of A using the corresponding entries in  $\mathbf{x}$  as weights; that is,

$$A\mathbf{x} = [\mathbf{a}_1 \mathbf{a}_2 \dots \mathbf{a}_n] \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} = x_1 \mathbf{a}_1 + x_2 \mathbf{a}_2 + \dots + x_n \mathbf{a}_n$$

Example: #4, p. 47

$$\begin{bmatrix} 8 & 3 & -4 \\ 5 & 1 & 2 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \left[ 1 \cdot \begin{bmatrix} 7 \\ 5 \end{bmatrix} + \left[ 1 \cdot \begin{bmatrix} 3 \\ 2 \end{bmatrix} \right] + \left[ 1 \cdot \begin{bmatrix} -4 \\ 2 \end{bmatrix} \right]$$

We now have four ways of writing a system of equations(!), as given in

**Theorem Three** (p. 42): If A is an  $m \times n$  matrix, with columns  $\mathbf{a}_1$ ,  $\mathbf{a}_2 \dots$ ,  $\mathbf{a}_n$ , and if  $\mathbf{x}$  is in  $\mathbb{R}^n$ , the matrix equation

$$A\mathbf{x} = \mathbf{b}$$

has the same solution set as the vector equation

$$x_1\mathbf{a}_1 + x_2\mathbf{a}_2 + \ldots + x_n\mathbf{a}_n = \mathbf{b}$$

which, in turn, has the same solution set as the system of linear equations whose augmented matrix is

$$[\mathbf{a}_1 \quad \mathbf{a}_2 \quad \dots \quad \mathbf{a}_n \quad \mathbf{b}]$$

Example: #9, p. 47

$$3x_{1} + x_{2} - 5x_{3} = 9$$

$$x_{2} + 4x_{3} = 0$$

$$x_{1} \begin{bmatrix} 3 & 1 & -5 & 9 \\ 0 & 1 & 4 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 3 & 1 & -5 & 9 \\ 0 & 1 & 4 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 3 & 1 & -5 & 9 \\ 0 & 1 & 4 & 0 \end{bmatrix}$$

Existence of solutions is given by the following theorem:

**Theorem Four** (p. 43): Let A be an  $m \times n$  matrix. Then the following statements are logically equivalent. That is, for a particular A, either they are all true statements or they are all false.

- (i) For each **b** in  $\mathbb{R}^m$ , the equation  $A\mathbf{x} = \mathbf{b}$  has a solution.
- (ii) Each **b** in  $\mathbb{R}^m$  is a linear combination of the columns of A.
- (iii) The columns of A span  $\mathbb{R}^m$ .
- (iv) A has a pivot position in every row.

Example: #14, p. 48

Let 
$$u = \begin{bmatrix} 2 \\ -3 \\ 2 \end{bmatrix} + A = \begin{bmatrix} 5 & 8 & 7 \\ 0 & 1 & -1 \\ 1 & 3 & 0 \end{bmatrix}$$

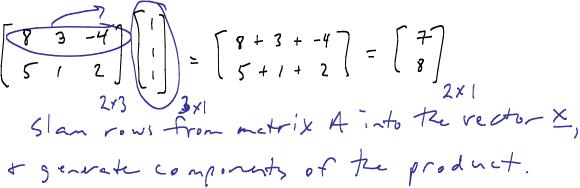
Is  $u = \begin{bmatrix} 5 & 7 & 7 & 2 \\ 0 & 1 & -1 & -3 \\ 1 & 3 & 0 & 2 \end{bmatrix}$ ,  $\begin{bmatrix} 5 \\ 0 \\ 1 \end{bmatrix} x_1 + \begin{bmatrix} 7 \\ 1 \\ 3 \end{bmatrix} x_2 + \begin{bmatrix} 7 \\ -1 \\ 0 \end{bmatrix} x_3 = \begin{bmatrix} 2 \\ -3 \\ 2 \end{bmatrix}$ 

Ax =  $u$ ;  $\begin{bmatrix} 5 & 7 & 7 & 2 \\ 0 & 1 & -1 & -3 \\ 1 & 3 & 0 & 2 \end{bmatrix}$ ,  $\begin{bmatrix} 5 \\ 0 \\ 1 \end{bmatrix} x_1 + \begin{bmatrix} 7 \\ 1 \\ 3 \end{bmatrix} x_2 + \begin{bmatrix} 7 \\ -1 \\ 0 \end{bmatrix} x_3 = \begin{bmatrix} 2 \\ -3 \\ 2 \end{bmatrix}$ 

A handy way to think about matrix multiplication: Row-Vector rule for computing  $A\mathbf{x}$ 

If the product  $A\mathbf{x}$  is defined, then the *ith* entry in the vector  $A\mathbf{x}$  (yes, it's a vector!) is the sum of the products of corresponding entries from row i of A and from the vector  $\mathbf{x}$ .

Example: Revisit #4, p. 47



**Theorem Five** (p. 45): If A is an  $m \times n$  matrix,  $\mathbf{u}$  and  $\mathbf{v}$  are vectors in  $\mathbb{R}^n$ , and c is a scalar, then:

(i) 
$$A(\mathbf{u} + \mathbf{v}) = A\mathbf{u} + A\mathbf{v}$$

(ii) 
$$A(c\mathbf{u}) = c(A\mathbf{u})$$

Example: #35, p. 49

A<sub>3×1</sub>; 
$$Y_{11}Y_{2} \in \mathbb{R}^{3}$$
;  $W = Y_{1} + Y_{2}$   
Suppose  $\exists x_{1} \text{ and } x_{2} / A_{x_{1}} = Y_{1} \text{ and } A_{x_{2}} = Y_{2}$ .  
How do we know that  $AX = Y_{1}$   
consistent?
$$A(X_{1} + X_{2}) = Ax_{1} + Ax_{2} = Y_{2}$$

$$X = Y_{1} + Y_{2} = W$$

 $A_{4} = 2$   $Ts \quad A_{x} = 42 \quad consistant ?$   $X = 44 \quad is \quad a \quad sola :$   $A(4_{4}) = 4(A_{4}) = 42$