

Section 7.1: Diagonalization of Symmetric Matrices

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Abstract

As we begin chapter seven (and finish up the semester!), we should keep track of our specific objectives (other than relaxing after finals). We've got two goals:

- (a) to analyze the structure of general matrices of information (like LandSat images, say, as described in the opening pages of the chapter, p. 447, or like statistical data sets) – we'll do this via the Singular Value Decomposition, wavelets, etc.; and
- (b) to examine the behavior of symmetric matrices (those that satisfy $A^T = A$) as linear transformations (it turns out that they're fundamental to goal (a)).

Great things happen when you work with symmetric matrices: their special structure leads to some seemingly magical properties. Symmetric matrices are an important special case, as we found in working with the least-squares problems (where the left-hand side was $A^T A$, a symmetric matrix!).

Theorem 1: If A is symmetric, then any two eigenvectors from different eigenspaces are orthogonal.

Comment: In the past, when a matrix had two distinct eigenvalues λ_1 and λ_2 , we could conclude that the corresponding eigenvectors were independent – but we couldn't conclude that the eigenvectors were orthogonal.

Example: #13, p. 454

Definition: *orthogonally diagonalizable* A matrix is orthogonally diagonalizable if there is an orthogonal matrix P and diagonal matrix D such that

$$A = PDP^T$$

Example: #22, p. 454

Theorem 2: $A_{n \times n}$ is orthogonally diagonalizable if and only if A is a symmetric matrix.

Theorem 3 (The Spectral Theorem): Symmetric $A_{n \times n}$ has the following properties:

- (a) A has n real eigenvalues, counting multiplicities (no complex eigenvalues!).
- (b) The dimension of the eigenspace for each eigenvalue λ equals the multiplicity of λ as a root of the characteristic equation (no “missing” dimensions).
- (c) The eigenspaces are mutually orthogonal: eigenvectors corresponding to different eigenvalues are orthogonal (no shadows cast on each other).

(d) A is orthogonally diagonalizable.

Let's look at the geometry of this: if we think about transforming the n -dimensional unit ball into an ellipsoid, then it turns out that the eigenvectors are the major/minor axes of the ellipsoid, and the eigenvalues are the stretch factors.

Example: #31, p. 455

$$A = \overset{P}{\begin{bmatrix} \mathbf{u}_1 & \dots & \mathbf{u}_n \end{bmatrix}} \overset{D}{\begin{bmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{bmatrix}} \overset{P^T}{\begin{bmatrix} \mathbf{u}_1^T \\ \vdots \\ \mathbf{u}_n^T \end{bmatrix}}$$

Since $A = PDP^T$, where p is an orthogonal matrix, we can write

$$A = \lambda_1 \mathbf{u}_1 \mathbf{u}_1^T + \lambda_2 \mathbf{u}_2 \mathbf{u}_2^T + \dots + \lambda_n \mathbf{u}_n \mathbf{u}_n^T,$$

the **spectral decomposition** of A . Each matrix $\mathbf{u}_j \mathbf{u}_j^T$ is a **projection matrix**: the projection of vector \mathbf{x} onto the subspace spanned by \mathbf{u}_j is given by

$$\text{proj}_{\mathbf{u}_j} \mathbf{x} = \mathbf{u}_j \mathbf{u}_j^T \mathbf{x} = (\mathbf{x} \cdot \mathbf{u}_j) \mathbf{u}_j$$

(the last part of the equation is one way of thinking of the projection that I've emphasized).

Example: #34, p. 455

$$A = \begin{bmatrix} 3 & -2 & 4 \\ -2 & 4 & 2 \\ 4 & 2 & 3 \end{bmatrix} = 7 \begin{bmatrix} \frac{1}{\sqrt{2}} \\ 0 \\ \frac{1}{\sqrt{2}} \end{bmatrix} \begin{bmatrix} \frac{1}{\sqrt{2}} & 0 & \frac{1}{\sqrt{2}} \end{bmatrix} + 7 \begin{bmatrix} -\frac{1}{\sqrt{13}} \\ \frac{4}{\sqrt{13}} \\ \frac{1}{\sqrt{13}} \end{bmatrix} \begin{bmatrix} -\frac{1}{\sqrt{13}} & \frac{4}{\sqrt{13}} & \frac{1}{\sqrt{13}} \end{bmatrix} + -2 \begin{bmatrix} -\frac{2}{3} \\ -\frac{1}{3} \\ \frac{2}{3} \end{bmatrix} \begin{bmatrix} -\frac{2}{3} & -\frac{1}{3} & \frac{2}{3} \end{bmatrix}$$

The action of A as a linear transformation is well understood, therefore:

$$A\mathbf{x} = \lambda_1 \mathbf{u}_1 \mathbf{u}_1^T \mathbf{x} + \lambda_2 \mathbf{u}_2 \mathbf{u}_2^T \mathbf{x} + \dots + \lambda_n \mathbf{u}_n \mathbf{u}_n^T \mathbf{x},$$

or

$$A\mathbf{x} = (\lambda_1 \mathbf{u}_1^T \mathbf{x}) \mathbf{u}_1 + (\lambda_2 \mathbf{u}_2^T \mathbf{x}) \mathbf{u}_2 + \dots + (\lambda_n \mathbf{u}_n^T \mathbf{x}) \mathbf{u}_n.$$

That is, we project \mathbf{x} onto each basis vector, and then multiply each of these projections by the corresponding eigenvalue. Alternatively, if

$$\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}_P$$

where P represents the basis composed of its columns, then

$$A\mathbf{x} = \begin{bmatrix} \lambda_1 x_1 \\ \lambda_2 x_2 \\ \vdots \\ \lambda_n x_n \end{bmatrix}_P$$

Neat!